

Outline

- Best-first search
 - Greedy best-first search
 - A* search
 - Heuristics
- Local search algorithms
 - Hill-climbing search
 - Beam search
 - Simulated annealing search
 - Genetic algorithms
- **Constraint Satisfaction Problems**

Constraint Satisfaction Problems

Special Type of search problem:

- state is defined by **variables** X_i with **values** from **domain** D_i
- goal test** is a set of **constraints** specifying allowable combinations of values for subsets of variables

Examples:

- Sudoku

5	3			7					
6			1	9	5				
	9	8						6	
8				6					3
4			8		3				1
7				2					6
	6						2	8	
			4	1	9				5
				8				7	9

5	3	4	6	7	8	9	1	2	
6	7	2	1	9	5	3	4	8	
1	9	8	3	4	2	5	6	7	
8	5	9	7	6	1	4	2	3	
4	2	6	8	5	3	7	9	1	
7	1	3	9	2	4	8	5	6	
9	6	1	5	3	7	2	8	4	
2	8	7	4	1	9	6	3	5	
3	4	5	2	8	6	1	7	9	

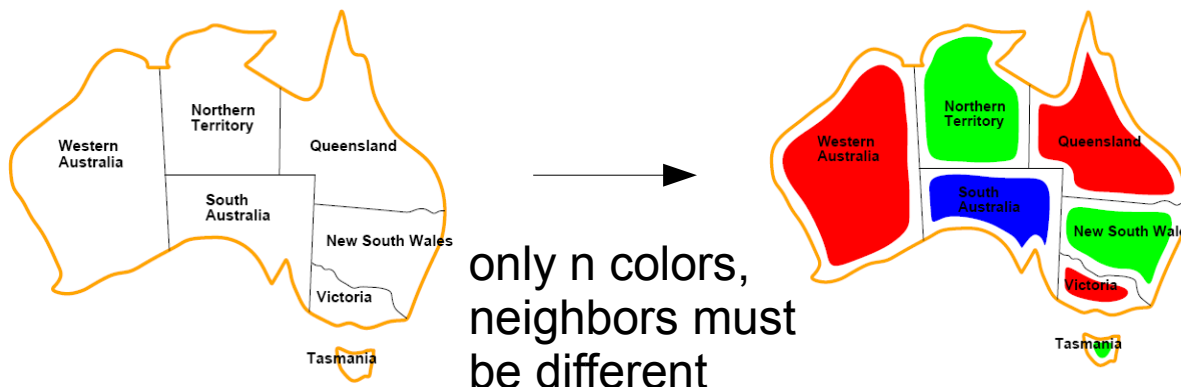
- cryptarithmic puzzle

SEND
+ MORE

MONEY

- n-queens

- Graph/Map-Coloring

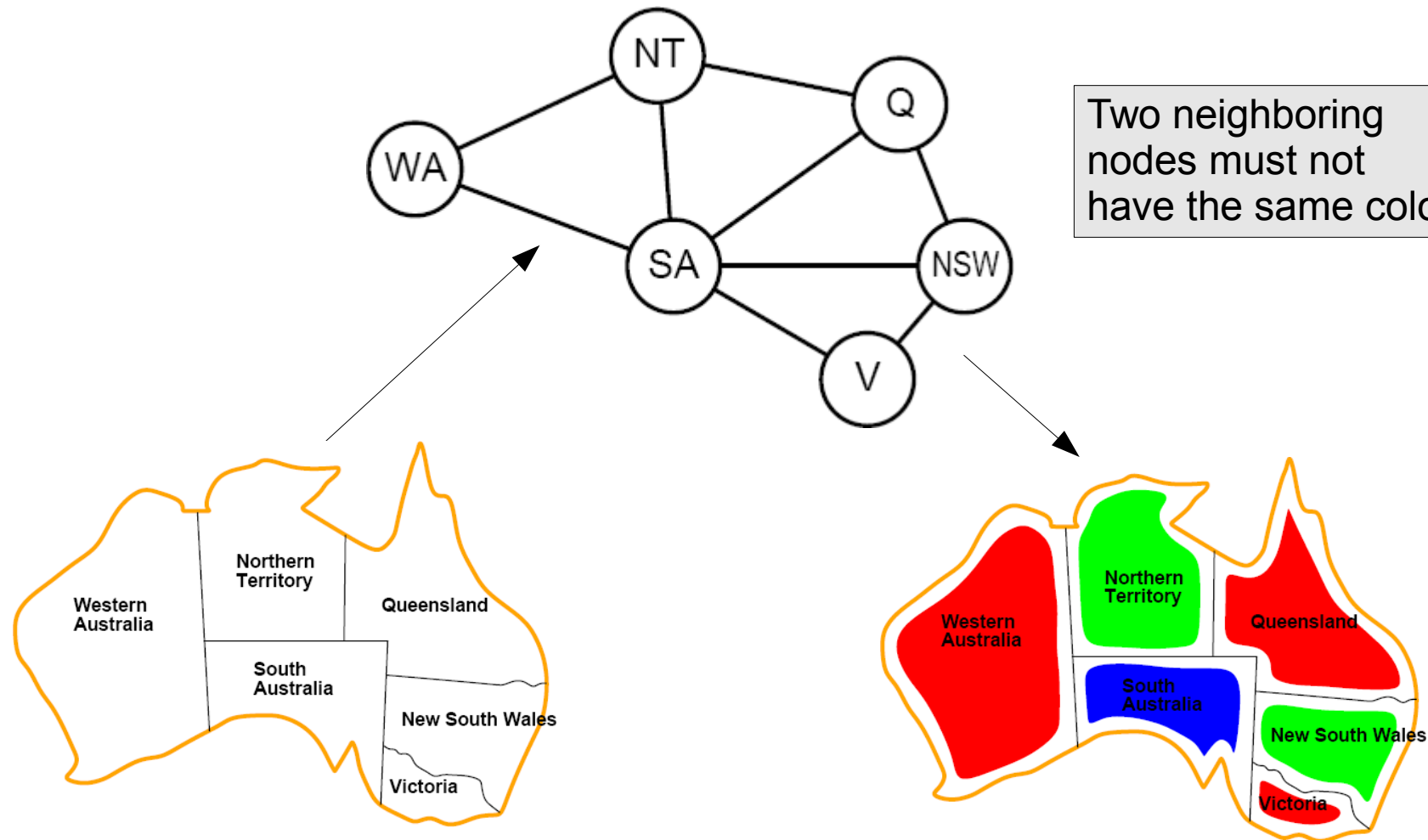


- Real-world:

- assignment problems
- timetables
 - classes, lecturers
 - rooms, studies
- ...

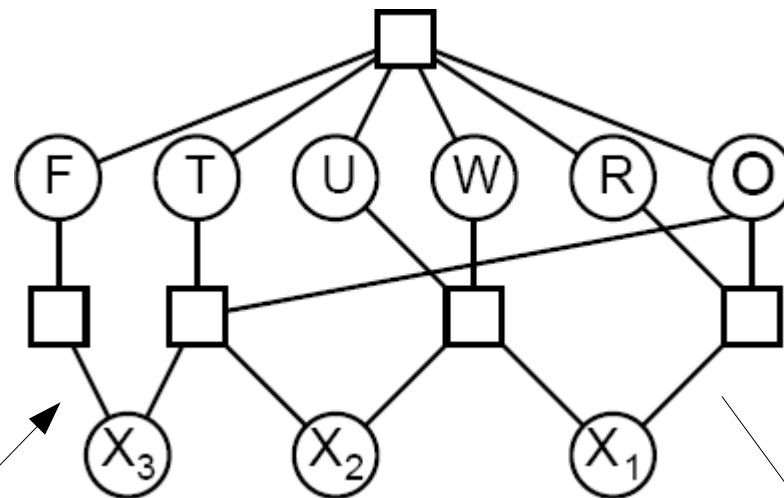
Constraint Graph

- nodes are variables
- edges indicate constraints between them



Constraint Graph

- nodes are variables
- edges indicate constraints between them



Connected nodes are involved in (in-)equations:

$$2 \cdot O = 10 \cdot X_1 + R$$

$$2 \cdot W + X_1 = 10 \cdot X_2 + U$$

$$2 \cdot T + X_2 = 10 \cdot X_3 + O$$

$$F = X_3$$

$$F \neq T \neq U \neq W \neq R \neq O$$

$$\begin{array}{r} \text{T W O} \\ + \text{T W O} \\ \hline \text{F O U R} \end{array}$$

$$\begin{array}{r} 734 \\ + 734 \\ \hline 1468 \end{array}$$

Types of Constraints

- **Unary** constraints involve a single variable,
 - e.g., *South Australia \neq green*
- **Binary** constraints involve pairs of variables,
 - e.g., *South Australia \neq Western Australia*
- **Higher-order** constraints involve 3 or more variables
 - e.g., $2 \cdot W + X_1 = 10 \cdot X_2 + U$
- **Preferences** (soft constraints)
 - e.g., *red is better than green*
 - are not binding, but task is to respect as many as possible
→ constrained optimization problems

Backtracking Search

- CSP are typically solved with backtracking
 - add one constraint at a time without conflict
 - succeed if a legal assignment is found

```

function BACKTRACKING-SEARCH(csp) returns solution/failure
  return RECURSIVE-BACKTRACKING({ }, csp)

function RECURSIVE-BACKTRACKING(assignment, csp) returns soln/failure
  if assignment is complete then return assignment
  var ← SELECT-UNASSIGNED-VARIABLE(VARIABLES[csp], assignment, csp)
  for each value in ORDER-DOMAIN-VALUES(var, assignment, csp) do
    if value is consistent with assignment given CONSTRAINTS[csp] then
      add {var = value} to assignment
      result ← RECURSIVE-BACKTRACKING(assignment, csp)
      if result ≠ failure then return result
      remove {var = value} from assignment
  return failure
  
```

Worst-Case Complexity of Backtracking Search

- Assumptions
 - we have n variables
 - all solutions are a depth n in the search tree
 - all variables have v possible values
 - Then
 - at level 1 we have $n \cdot v$ possible assignments
 - (we can choose one of n variables and one of v values for it)
 - at level 2, we have $(n-1) \cdot v$ possible assignments for each previously assigned variable
 - (we can choose one of the remaining $n-1$ variables and one of the v values for it)
 - In general: branching factor at depth l : $(n-l+1) \cdot v$
 - Hence
 - The search tree has $n!v^n$ leaves
- heuristics are needed in SELECT-UNASSIGNED-VARIABLE

General Heuristics for CSP

- **Domain-Specific Heuristics**
 - Depend on the particular characteristics of the problem
 - Obviously, a heuristic for the 8-puzzle can not be used for the 8-queens problem
- **General-purpose heuristics**
 - For CSP, good general-purpose heuristics are known:
 - **Minimum Remaining Value Heuristic**
 - choose the variable with the fewest consistent values
 - **Degree Heuristic**
 - choose the variable that imposes the most constraints on the remaining values
 - **Least Constraining Value Heuristic**
 - Given a variable, choose the value that rules out the fewest values in the remaining variables
 - used in this order, these three can greatly speed up search
 - e.g., n-queens from 25 queens to 1000 queens

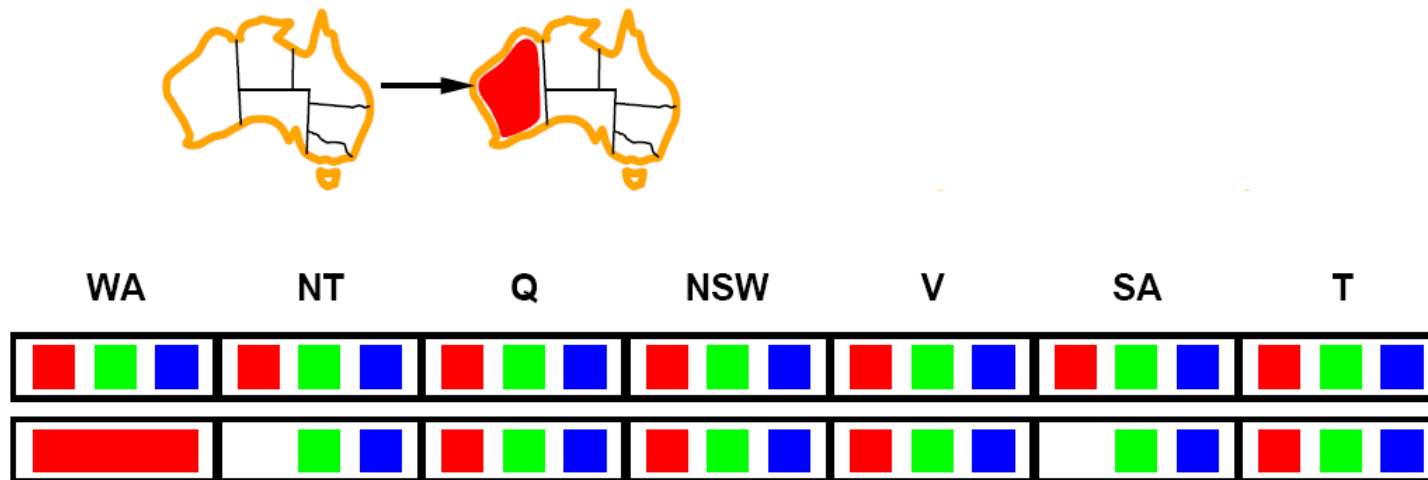
Forward Checking

- Idea:
 - keep track of remaining legal values for unassigned variables
 - terminate search when any variable has no more legal values



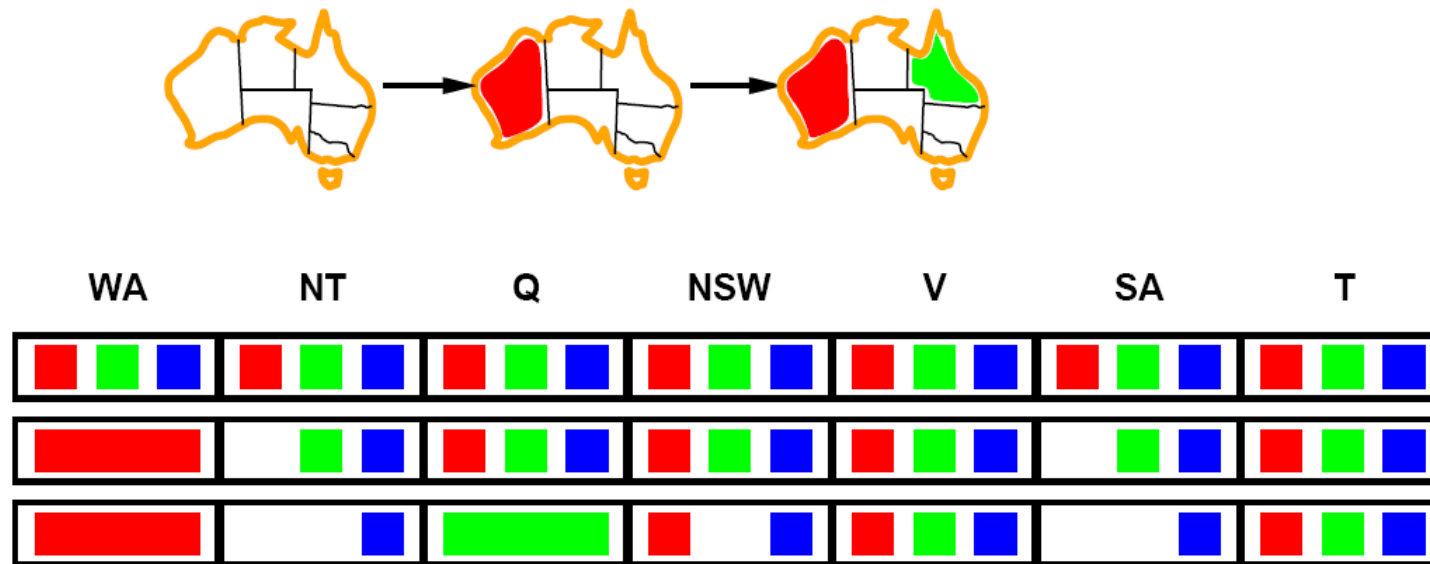
Forward Checking

- Idea:
 - keep track of remaining legal values for unassigned variables
 - terminate search when any variable no legal values



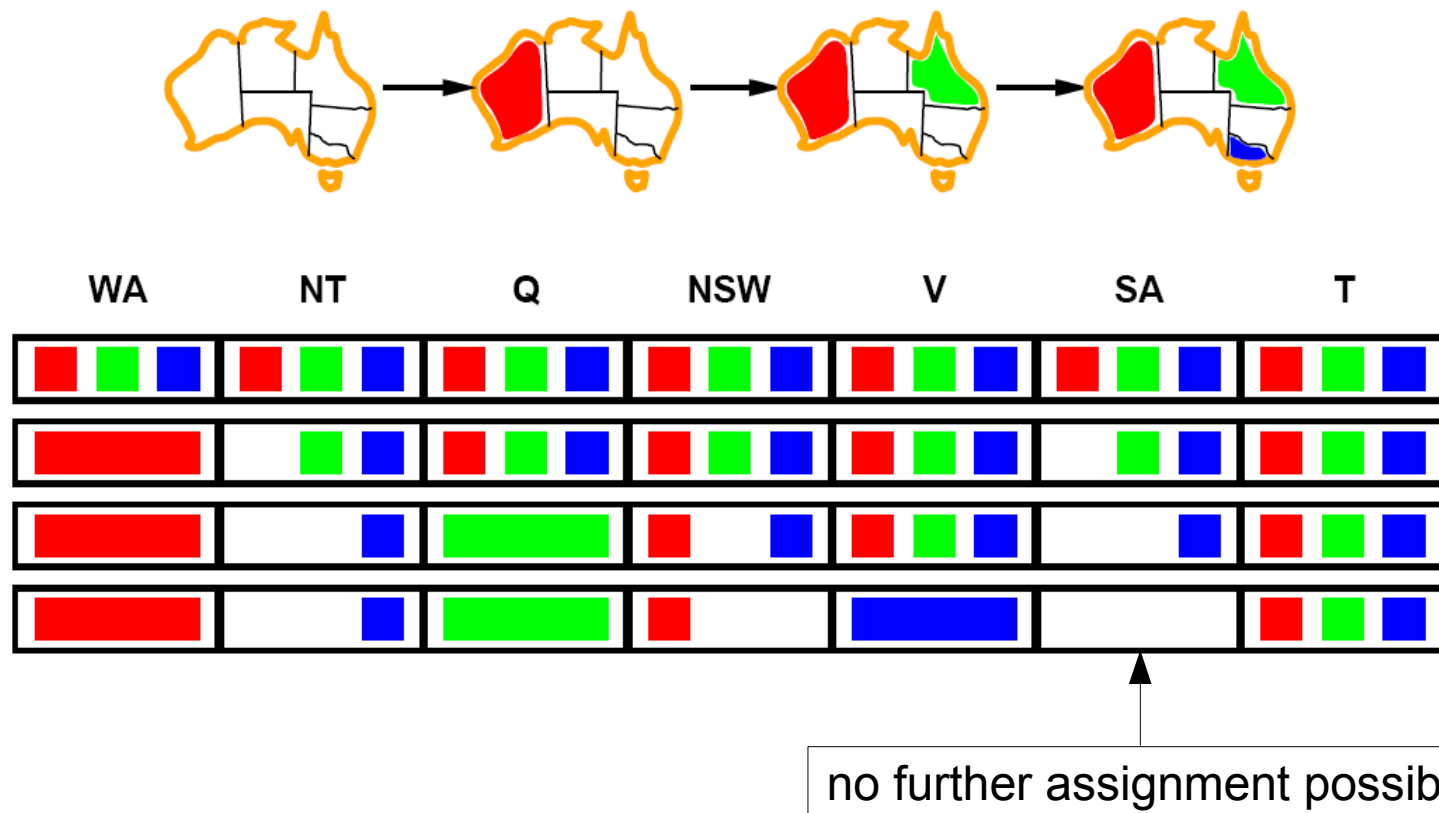
Forward Checking

- Idea:
 - keep track of remaining legal values for unassigned variables
 - terminate search when any variable no legal values



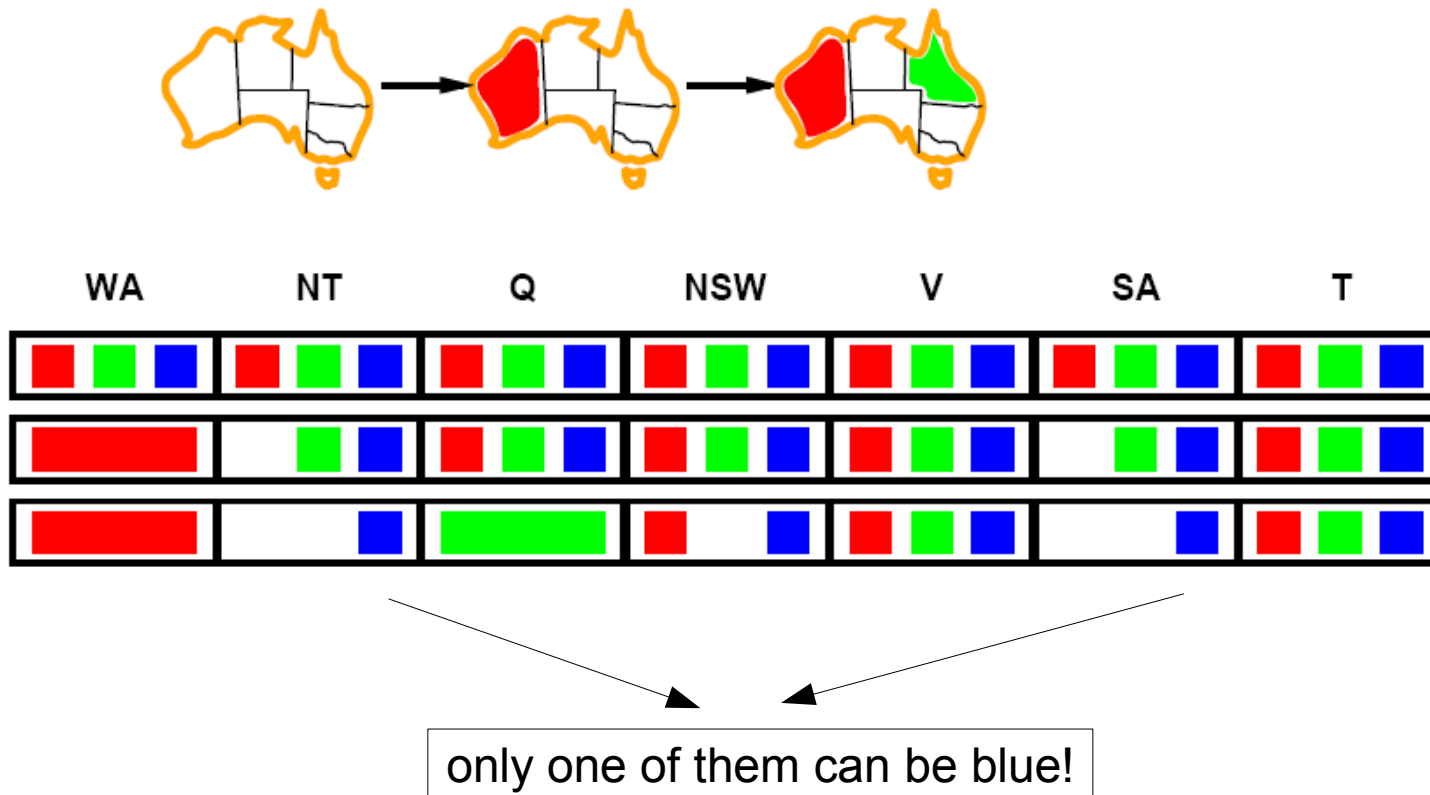
Forward Checking

- Idea:
 - keep track of remaining legal values for unassigned variables
 - terminate search when any variable no legal values



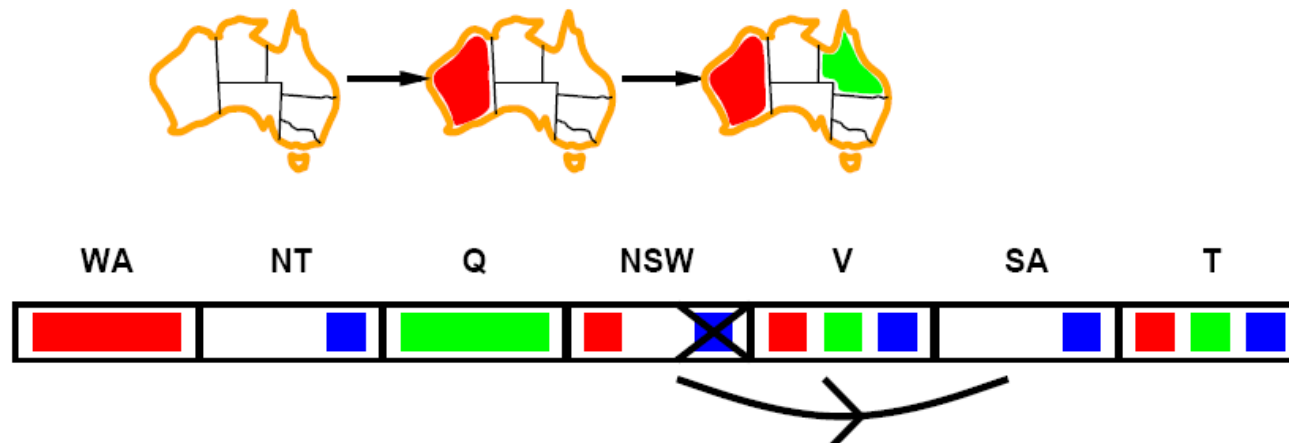
Constraint Propagation

- Problem:
 - forward checking propagates information from assigned to unassigned variables
 - but doesn't provide early detection for all failures

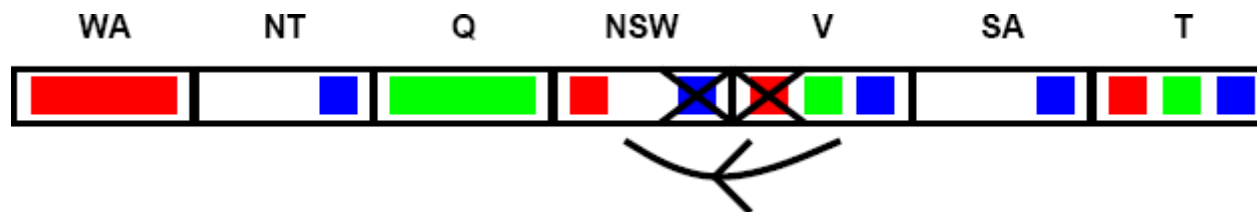


Arc Consistency

A binary constraint between variables X and Y is **consistent** iff for every value of X , there is some legal value for Y



- If one variable (NSW) loses a value (blue), we need to recheck its neighbors as well:



Arc Consistency Algorithm

function AC-3(*csp*) **returns** the CSP, possibly with reduced domains

inputs: *csp*, a binary CSP with variables $\{X_1, X_2, \dots, X_n\}$

local variables: *queue*, a queue of arcs, initially all the arcs in *csp*

while *queue* is not empty **do**

$(X_i, X_j) \leftarrow \text{REMOVE-FIRST}(\textit{queue})$

if REMOVE-INCONSISTENT-VALUES(X_i, X_j) **then**

for each X_k **in** NEIGHBORS[X_i] **do**

 add (X_k, X_i) to *queue*

If X loses a value,
neighbors of X need
to be rechecked.

function REMOVE-INCONSISTENT-VALUES(X_i, X_j) **returns** true iff succeeds

removed \leftarrow false

for each x **in** DOMAIN[X_i] **do**

if no value y in DOMAIN[X_j] allows (x, y) to satisfy the constraint $X_i \leftrightarrow X_j$

then delete x from DOMAIN[X_i]; *removed* \leftarrow true

return *removed*

- Run-time: $O(n^2 d^3)$ (can be reduced to $O(n^2 d^2)$)
more efficient than forward checking

Local Search for CSP

- **Modifications** for CSPs:
 - work with complete states
 - allow states with unsatisfied constraints
 - operators reassign variable values
- **Min-conflicts Heuristic:**
 - randomly select a conflicted variable
 - choose the value that violates the fewest constraints
 - hill-climbing with $h(n) = \#$ of violated constraints
- **Performance:**
 - can solve randomly generated CSPs with a high probability
 - except in a narrow range of

$$R = \frac{\text{number of constraints}}{\text{number of variables}}$$

